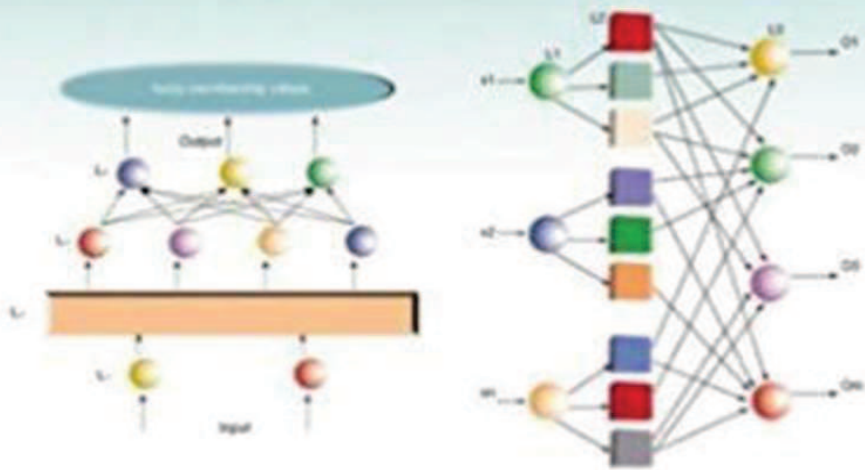


Computer Vision and Fuzzy-Neural Systems



ARUN D. KULKARNI

Computer Vision and Fuzzy-Neural Systems

ARUN D. KULKARNI

Complete guide to applying fuzzy-neural systems in computer vision

neural networks and fuzzy logic are trans- of computer vision, making it possible for applications to learn and make decisions, and visual data far more effectively. Now, Dr. Arun together the latest research and applications. d's first comprehensive tutorial and reference.

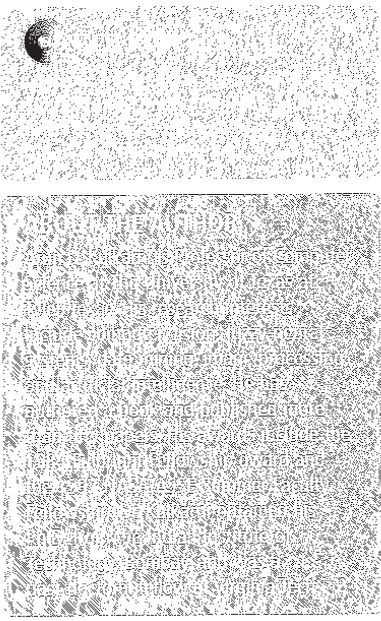
y reviewing the fundamentals of computer tages of a computer vision system. He shows rationally have been implemented via ques; then he introduces approaches that al networks, fuzzy inference systems, and work models. Coverage includes:

techniques such as radiometric or geometric

tion, supervised and unsupervised classification, omories, and other techniques for improving performance

vision applications: remote sensing, medical pression, data mining, character recognition, nd more

on and Fuzzy-Neural Systems illuminates state-of-the-art technology through hands-on exercises, ples, and proven algorithms. It is an essential resource for every engineer, scientist, and programmer puter vision and a wide range of related fields. It can also be used as a textbook for undergraduate- or ourses in computer vision.



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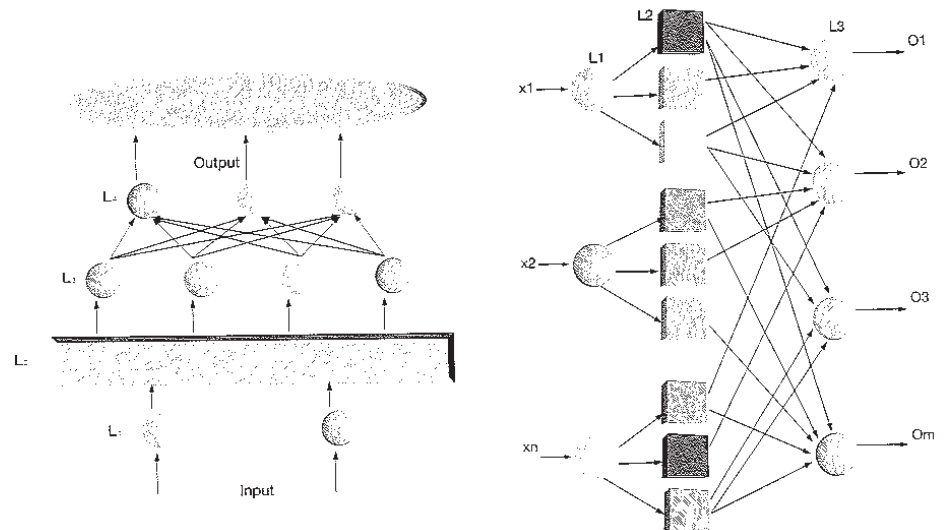


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PH PTR

ARUN D. KULKARNI

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Arun D. Kulkarni



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This book is dedicated to the memory of my parents

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PREFACE

Computer vision deals with extracting meaningful descriptions of physical objects from images. Computer vision has many practical applications such as remote sensing, medical image processing, robot vision, military reconnaissance, mineral exploration, cartography, forestry, etc. Recent developments in neural networks and fuzzy logic have changed the computer vision field dramatically. During the past few years there has been a large and energetic upswing in research efforts aimed at synthesizing fuzzy logic with neural networks. Neural networks provide algorithms for learning and are modeled after the physical architecture of the brain. Fuzzy logic deals with issues such as reasoning at the semantic or linguistic level and is based on the way brain deals with inexact information. Consequently, the two technologies complement each other. A variety of fuzzy-neural network models have been used in computer vision. This book deals with the topic of fuzzy-neural systems as applied to computer vision. The book provides exercises at the end of each chapter, and it can be used as a textbook for a course in computer vision at senior undergraduate or master degree level. The book also provides engineers, scientists, researchers, and students involved in computer vision a comprehensive, well-organized, up-to-date overview of recent techniques used in computer vision. The book is the outgrowth of my lecture notes in various classes that I taught at The University of Texas at Tyler. The material in the book is well tested in the classroom. It also has been published as journal articles and has been presented at various professional meetings.

Every effort has been made to produce a book that is easy to understand without oversimplification of the material. The mathematical level is well within grasp of a first-year graduate in a technical discipline such as engineering, computer science, or technology requiring preparation in classical set theory, discrete mathematics, matrix algebra, and computer programming. The textbook presents several worked-out examples along with MATLAB examples. All chapters contain exercises.

AUDIENCE

This book is intended for use as a textbook for courses in computer vision, pattern recognition, or image processing at either the senior undergraduate level or first year graduate level. It is also suitable for use as a self-study guide by researchers, professionals, or engineers who want to learn about recent advances in computer vision and fuzzy-neural systems. Many techniques described in the book are also useful in data mining.

ORGANIZATION

The book consists of ten chapters. Chapter 1 provides the overview of the book. Chapter 2 describes the fundamentals of computer vision. It describes various stages of a computer vision system. These stages can be implemented with conventional statistical techniques, neural networks, fuzzy inference systems, or fuzzy-neural network models. Chapter 3 and Chapter 4 describe fuzzy logic and neural network models, respectively. Chapter 5 describes pre-processing techniques such as radiometric or geometric corrections. Chapter 6 deals with feature extraction. Chapter 7 and Chapter 8 deal with supervised and unsupervised classification. Chapter 9 concerns with associative memories, and Chapter 10 presents various applications of computer vision. Topics such as remote sensing, medical image processing, data compression, data mining, character recognition, and stereovision are discussed in Chapter 10. The dependency chart for the chapters is shown in Figure P.1. The book covers material for two semesters in computer vision. Chapters 1 through 5 can be covered in the first semester and Chapters 6 through 10 can be covered during the second semester. For a one-semester course Chapters 1, 2, 3, 4, 5, 7, and 10 can be covered.

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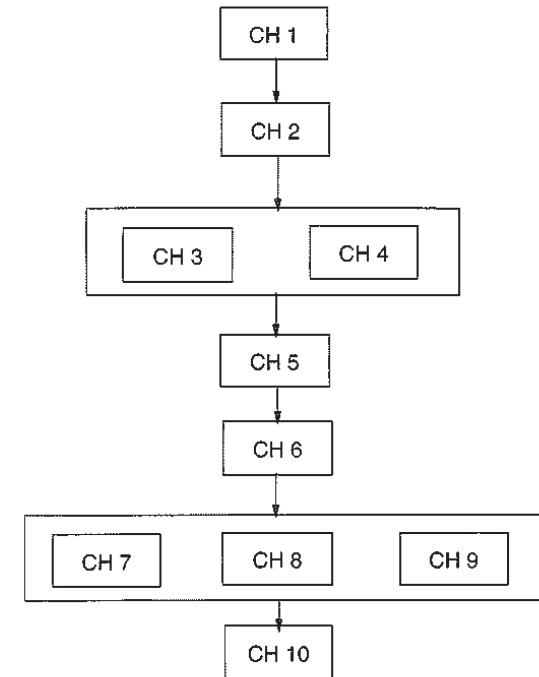


Figure P.1 Chapter dependency diagram

Complete guide to applying fuzzy-neural systems in computer vision, introducing approaches that incorporate neural networks, fuzzy inference systems and fuzzy-neural network models into the fundamental models of computer vision systems. The CD-ROM features a library of MATLAB command files and other files for the text. System requirements not listed. DLC: Computer vision. Start by marking "Computer Vision and Fuzzy-Neural Systems [With CDROM]" as Want to Read: Want to Read savingâ€¦! Want to Read.Â See a Problem? Weâ€™d love your help. Let us know whatâ€™s wrong with this preview of Computer Vision and Fuzzy-Neural Systems [With CDROM] by Arun D. Kulkarni. Problem: Itâ€™s the wrong book Itâ€™s the wrong edition Other. A blog about computer vision and serious stuff. Advertisements. Convolutional Neural Networks in Robotics. Posted by Gooly. by Li Yang Ku (Gooly).Â Traditional policy search approaches in reinforcement learning usually use the output of a "computer vision systems" and send commands to low-level controllers such as a PD controller. In the paper "end-to-end training of deep visuomotor policies", Sergey, et al. try to learn a policy from low-level observations (image and joint angles) and output joint torques directly. The overall architecture is shown in the figure above. As you can tell this is ambitious and cannot be easily achieved without a few tricks.